Planet Calibration and Interoperability ___The Planet Team, Planet Labs, Inc.



Otago, New Zealand - July 31, 2019

Current products The Planet Team, Planet Labs, Inc.

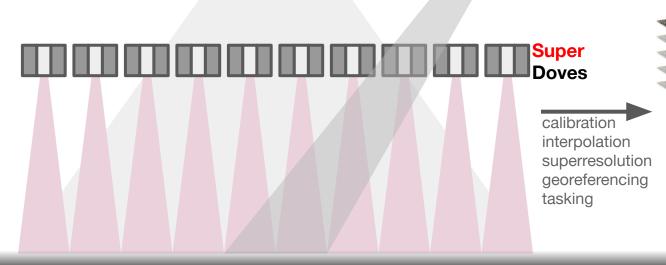


Otago, New Zealand – July 31, 2019

interoperability is usability



Hyperion EnMAP SkySat WorldView TerraSAR-X Sentinel-1

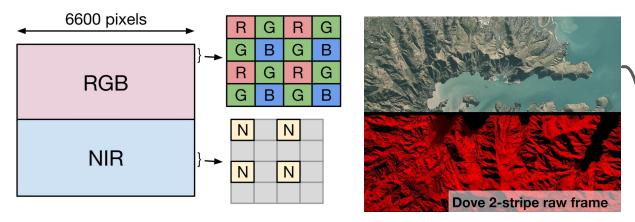


harmonized stacks that are more than the sum of the parts

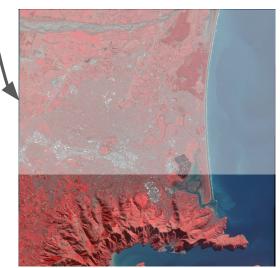
ARD strategy processing levels

Level	motto	Dove	SkySat	RE	Sentinel-2	MODIS	Landsat-8	HLS	latency	geometry	radiometry	delivery
LO	raw	raw f	rames									
L1a	raw video frames	cted at	ically-corre -sensor ance	sensor					3 hour	GO	RO	internal, R&D
L1b NRT	ortho ready	rec [:] sensor	gistered, tified -space, ed, TOAR		as provided NRT L1 TOAR products					G1	R1	catalog , orders API
L2v XYZ	visual	CIE XYZ (color-space,	e, 8- or 16-bit, with color profiles, TOAR-based, web-mercator or UTM-projected							R3	orders API
L2b ARD	SR+ <u>GRI</u> *	6SV-cc	prrected via N	IODIS/VIIR	S, UTM projec	ted, with R	SRs and SBAF	12 hours	G2		catalog , orders API	
L3h HLS	timeseries	har	monized to H	ed to HLS/sen2like, gap-filled, cloud-masked, CESTEM-based, polygon-based, streamable					HOUIS		R2	orders API
L3c CRD	streaming	8-bit c	urved TOAR,	AR, chips, image pyramid flat catalog, 3D geometry descriptors								orders API
L3d LAS	3D mesh	TBD 3D mesh from single capture 7.5km x 7.5km							1 day	G3	R5	orders API

Dove Classic sensor layout



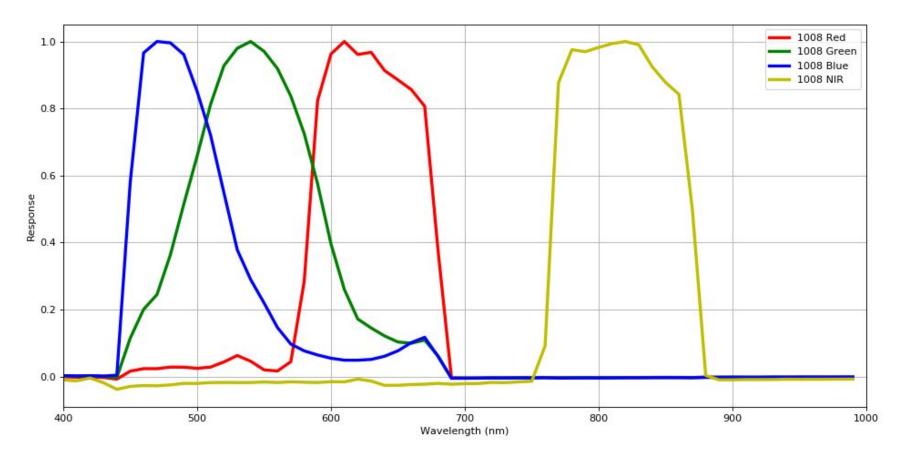
orthorectification



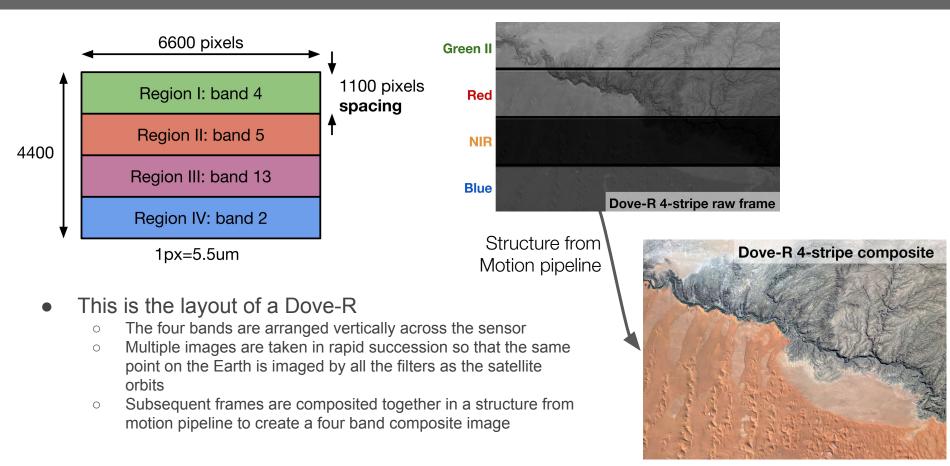
2-stripe half-frame composite

- This is the layout of the two-stripe Dove
 - The top stripe contains the red, blue and green bands in a Bayer pattern
 - The bottom stripe contains the NIR band
 - The orthorectification process allows a four band composite image to be produced

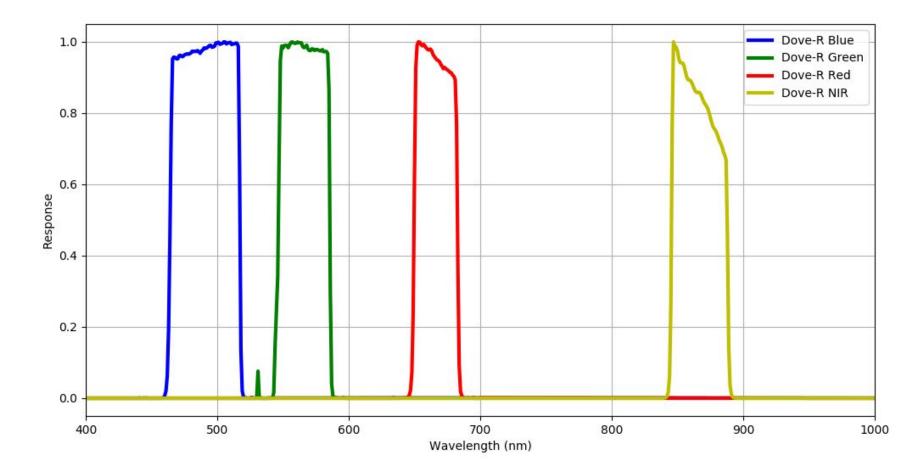
Typical Dove Classic RSR (measured at 10nm resolution)



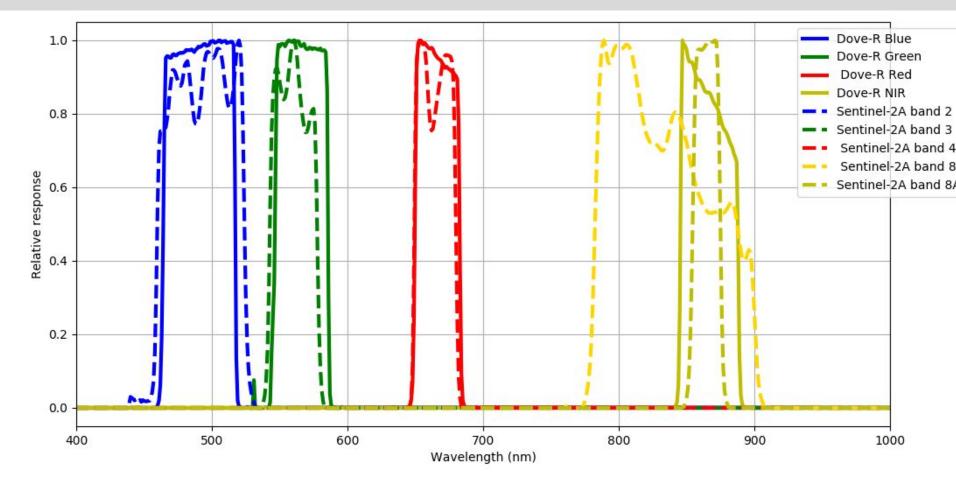
Dove-R sensor layout



Typical Dove-R RSR (from manufacturer data)

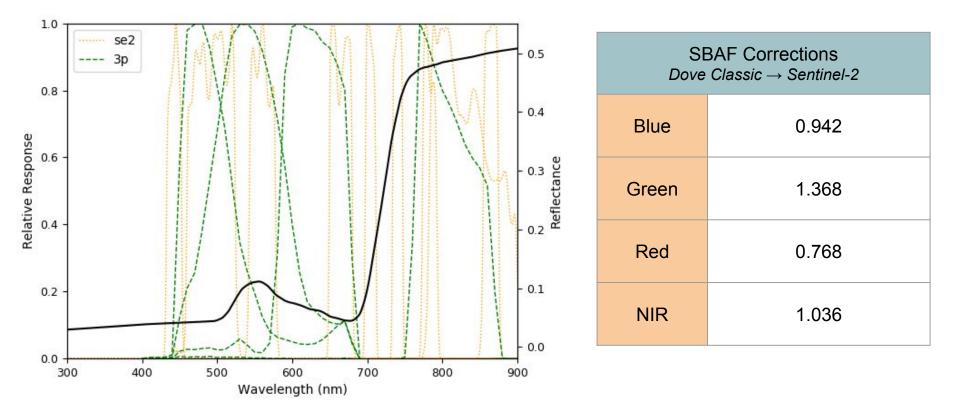


RSR compared to Sentinel-2A



Effects of Differing Responses: Dove Classic

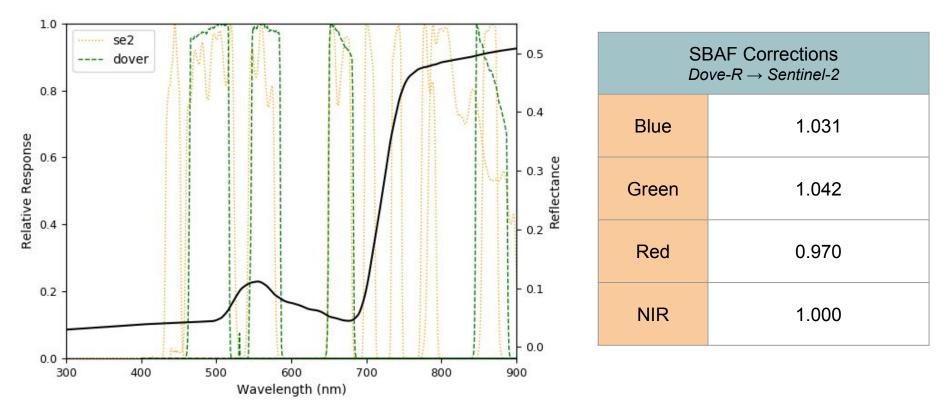
RSR vs Surface Spectrum: Green Grass



Calculating the spectral band adjustment factors between Sentinel-2 and Dove Classic

Effects of Differing Responses: Dove-R

RSR vs Surface Spectrum: Green Grass



Calculating the spectral band adjustment factors between Sentinel-2 and Dove-R

Current calibration process

Iguazú National Park, Brazil – September 23, 2016

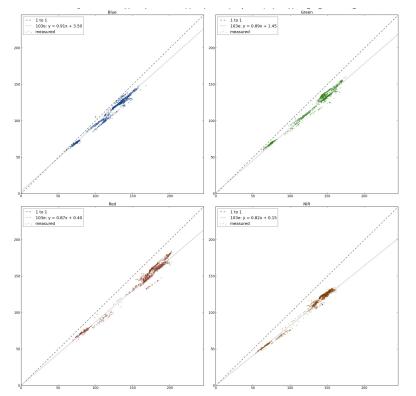


Calibration Approach

Cross Calibrating Doves to RapidEye

- Instantaneous crossovers sampled, corrected, and stored.
 - Crossovers sourced from RapidEye (RE) and Dove to Dove Crossovers if RE data lacking
- Crossovers cover the brightness range from 50 to 150 watts/m-2 sr-1 um-1
- Average of 5 crossover events and 500 samples used per-satellite/band to update calibration



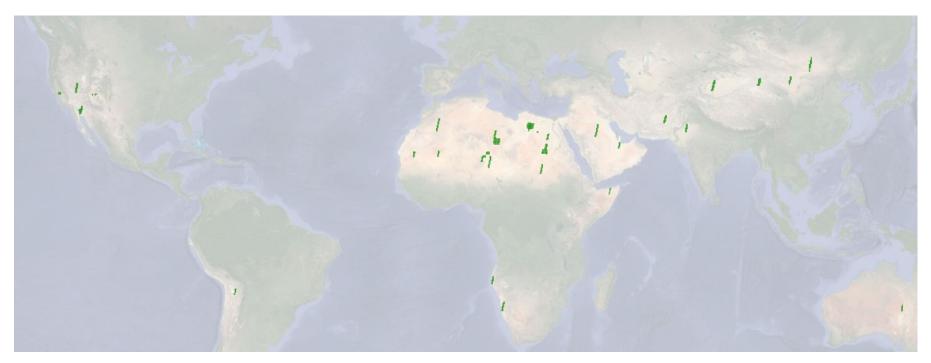


Calibration Sites

Globally distributed network of desert calibration sites

27 sites covering a range of bright and dark features to capture full dynamic range

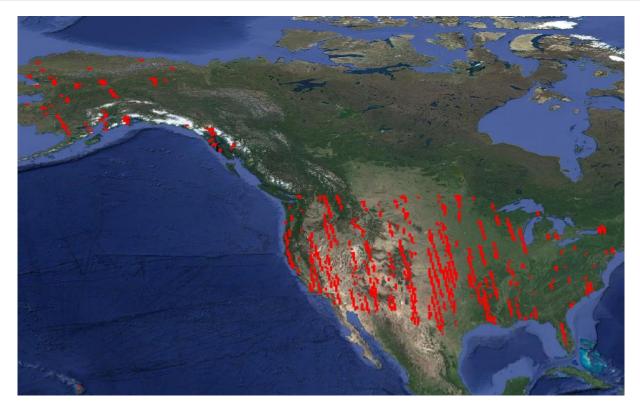




Revised calibration process

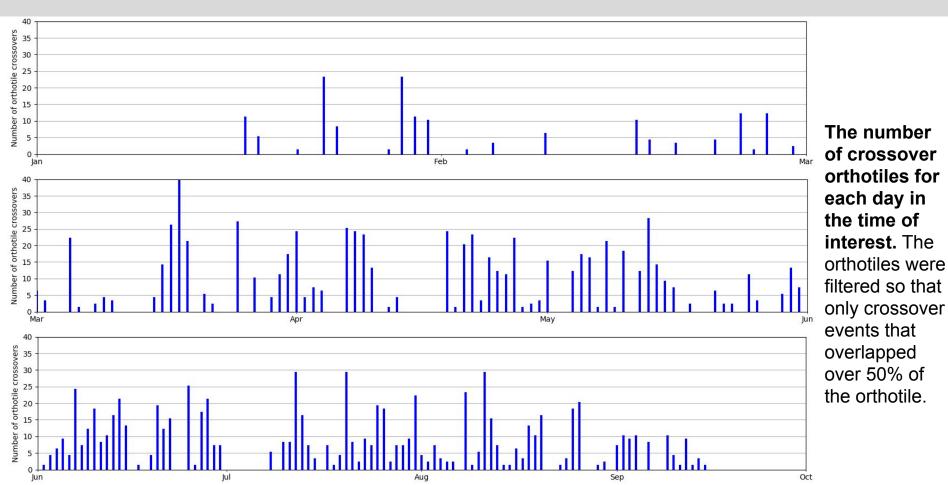
guazú National Park, Brazil – September 23, 2016

A summary of the crossovers for a single satellite



Showing the footprint of the crossovers for a single satellite. The entire set of crossovers was filtered using statistics to filter out the images affected by clouds.

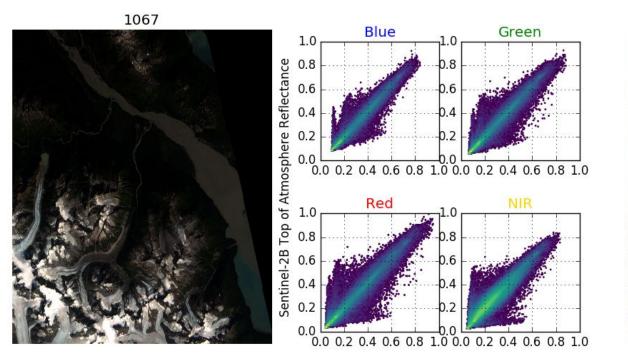
A timeline of the crossovers



Results for a single satellite

guazú National Park, Brazil – September 23, 2016

An example crossover

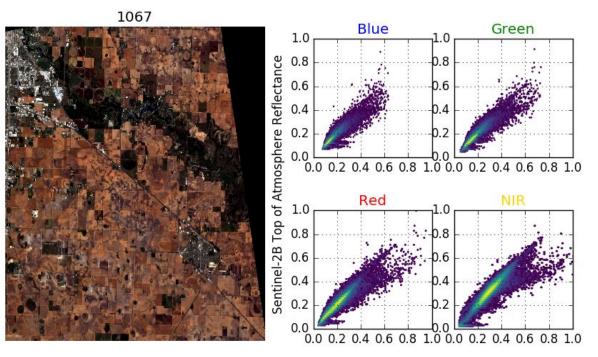


Sentinel-2B



1067 Top of Atmosphere Reflectance

An example crossover

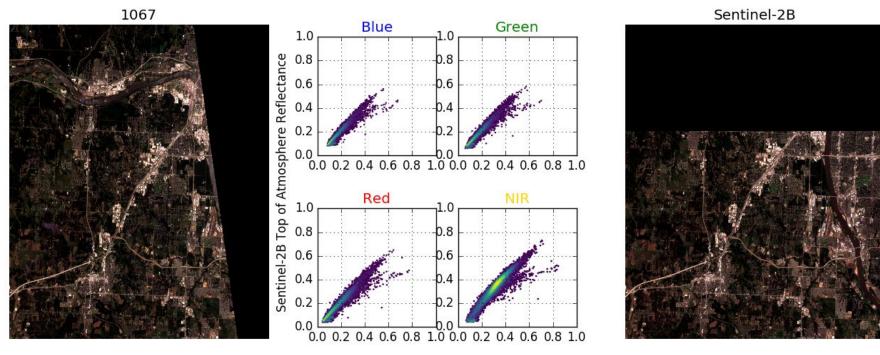


Sentinel-2B



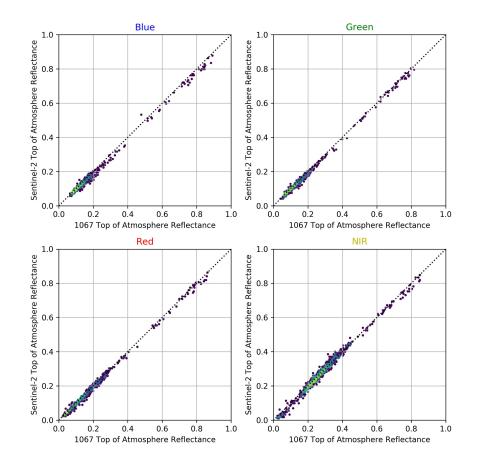
1067 Top of Atmosphere Reflectance

An example crossover



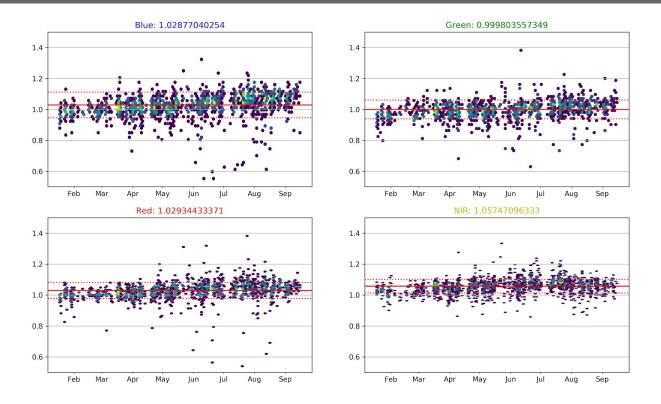
1067 Top of Atmosphere Reflectance

All the crossovers for a single satellite



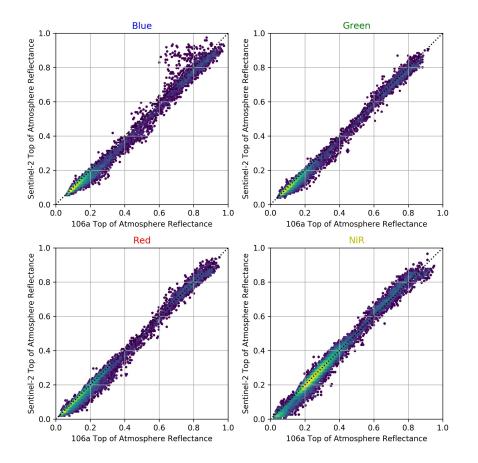
All 1644 orthotile events on a single plot. Each orthotile event was summarised as a single statistic in this scatter plot. The joint-mode of the candidate and reference measurements over the entire orthotile was chosen as the summary statistic (mirroring our own calibration process). The dynamic range of the dataset is much wider than with calibration sites, with a lot of data in over darker scenes. This reflects the data over terrain types where the data is frequently used (e.g. agricultural areas)

The fit of all the crossovers over time



Showing the range of fits over time. The fit between the reference and candidate measurements for each orthotile crossover event is shown to investigate if there is any seasonal variation.

All the crossovers for all Dove-Rs



All 33452 orthotile events for all satellites (over 257 days) on a single plot. The same filtering was done as for a single satellite.

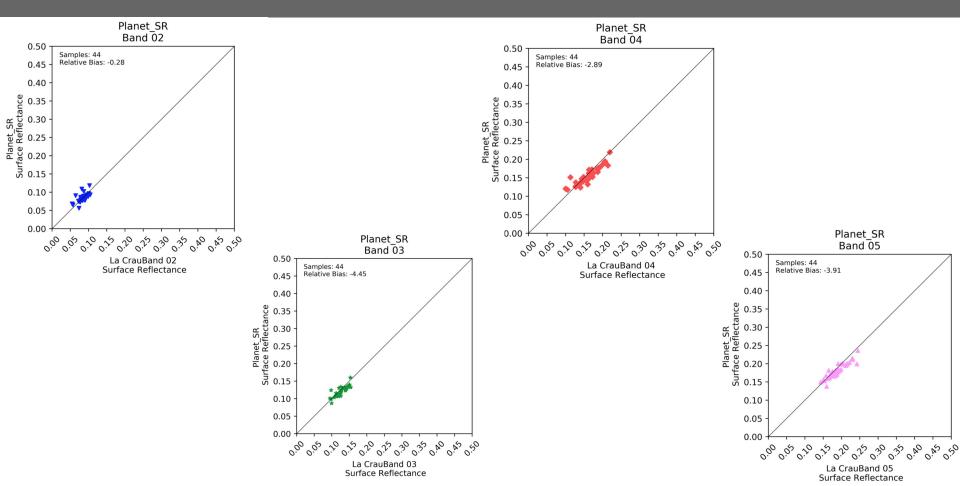
ARD strategy processing levels

Level	motto	Dove	SkySat	RE	Sentinel-2	MODIS	Landsat-8	HLS	latency	geometry	radiometry	delivery
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L1a	raw video frames	cted at	ically-corre -sensor ance	N/A			3 hour	GO	RO	internal, R&D		
L1b NRT	ortho ready	rec [:] sensor	L1b, registered, rectified sensor-space, geolocated, TOAR					6 hours	G1	R1	catalog , orders API	
L2v XYZ	visual	CIE XYZ color-space, 8- or 16-bit, with color profiles, TOAR-based, web-mercator or UTM-projected								R3	orders API	
L2b ARD	SR+ <u>GRI</u> *	6SV-corrected via MODIS/VIIRS, UTM projected, with RSRs and SBAF matrices							12	G2		catalog , orders API
L3h HLS	timeseries	harmonized to HLS/sen2like, gap-filled, cloud-masked, CESTEM-based, polygon-based, streamable							nours		R2	orders API
L3c CRD	streaming	8-bit curved TOAR, chips, image pyramid flat catalog, 3D geometry descriptors						6 hours			orders API	
L3d LAS	3D mesh	TBD 3D mesh from single capture 7.5km x 7.5km							1 day	G3	R5	orders API

Samples

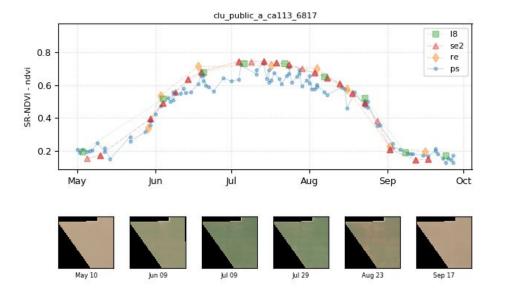
SkySat (collect) RapidEye (tile) Dove (partial strip) Dove-R (scene)

Results of the ACIX exercise



Results comparing Surface Reflectance

Time Series Comparison



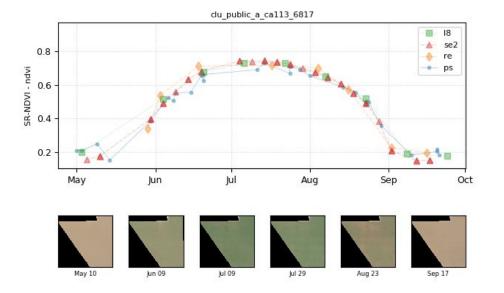
Collects from Sacramento Valley for summer 2019.

Includes imagery from Dove-C, Dove-R, RapidEye, Landsat-8 and Sentinel-2.

All results are from Planet's correction algorithm.

Results comparing Surface Reflectance

Time Series Comparison

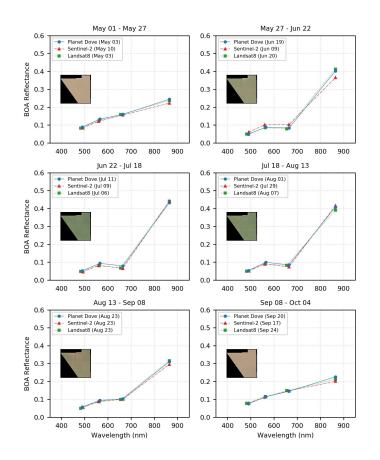


Collects from Sacramento Valley for summer 2019.

Includes imagery from Dove-R, RapidEye, Landsat-8 and Sentinel-2. *No Dove-C included*!

All results are from Planet's correction algorithm.

Results comparing Surface Reflectance



Time Series Comparison

Collects from Sacramento Valley for summer 2019.

Includes imagery from Dove-R, RapidEye, Landsat-8 and Sentinel-2. *No Dove-C included*!

All results are from Planet's correction algorithm.

Data quality reports The Planet Team, Planet Labs, Inc.



Otago, New Zealand – July 31, 2019

+ DATA QUALITY REPORTS AT PLANET Content

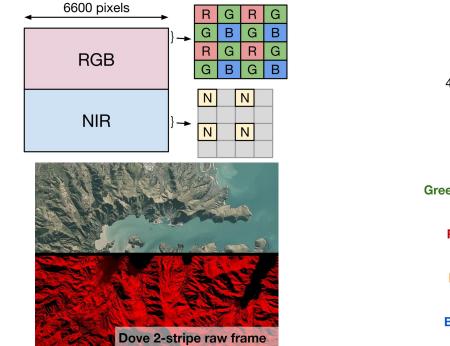
	L1 PS	L1 SSat	L2 PS		L1 PS	L1 SSat	L2 PS
Introduction	V	 	V	Radiom. Uncertainty	 	 	✓
Performance Overview	V	v	V	Interoperability	~		
Exposure Settings	V			Noise	 	 	
Geom. Reference Data	v	V		Focus	v	 	
Absolute Geolocation	v	 		Product Format	 	 	✓
Band Registration	v	 		Product Anomalies	 	 	✓
Temporal Registration	v	v		Pixel Status	 		
Relative Geolocation	 ✓ 	v		Product Features	~	 	V
Radiometric Status	v	v		Active Satellites	~		(p)
				·			

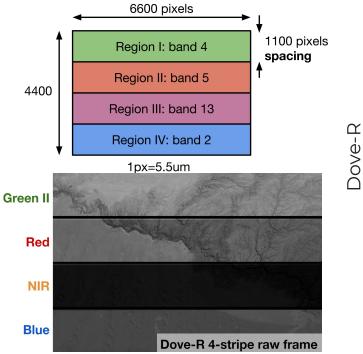
L1 Data Quality Report PlanetScope

Woody Island, South China Sea – March 28, 2018

PLANETSCOPE SATELLITES Dove-Classic and Dove-R (Refresh)

• Currently Dove-R makes up ~35% of the PlanetScope data





Dove

LI DATA QUALITY REPORT PLANETSCOPE Geometry

Shown Sic

Absolute Geolocation

Average RMSE rad	PCTL90(RMSE rad)	STD(RMSE rad)		
[m]	[m]	[m]		
3.6	6.8	2.3		

Temporal Registration

Average RMSE rad	PCTL90(RMSE rad)	STD(RMSE rad)
[m]	[m]	[m]
1.8	3.1	2.4

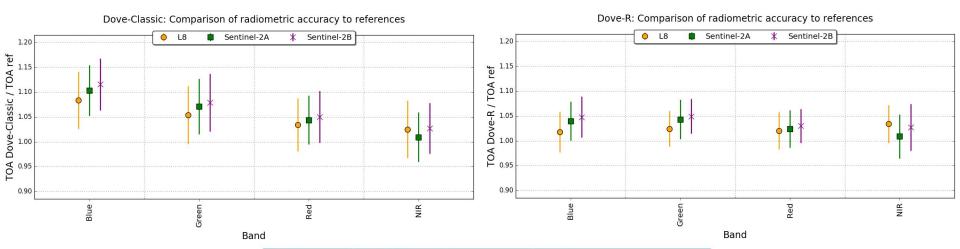
Relative Geolocation

Average RMSE rad	PCTL90(RMSE rad)	STD(RMSE rad)
[m]	[m]	[m]
1.2	2	1.6

Band Registration

Band Combination	Average RMSE rad [m]			
Blue - Green	0.140			
Blue - Red	0.158			
Blue - NIR	1.602			
Green - Red	0.160			
Green - NIR	1.550			
Red - NIR	1.671			

LI DATA QUALITY REPORT PLANETSCOPE Radiometry



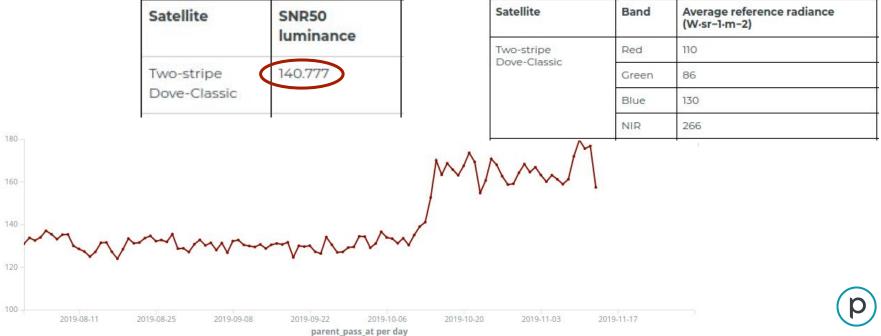
Band	Dove-Classic		Dove-R		
	Gain Coefficient	Standard Deviation	Gain Coefficient	Standard Deviation	
Blue	1.103	0.054	1.036	0.042	
Green	1.070	0.058	1. <mark>04</mark> 0	0.038	
Red	1.044	0.051	1.025	0.036	
NIR	1.019	0.052	1.021	0.045	

LI DATA QUALITY REPORT PLANETSCOPE Noise

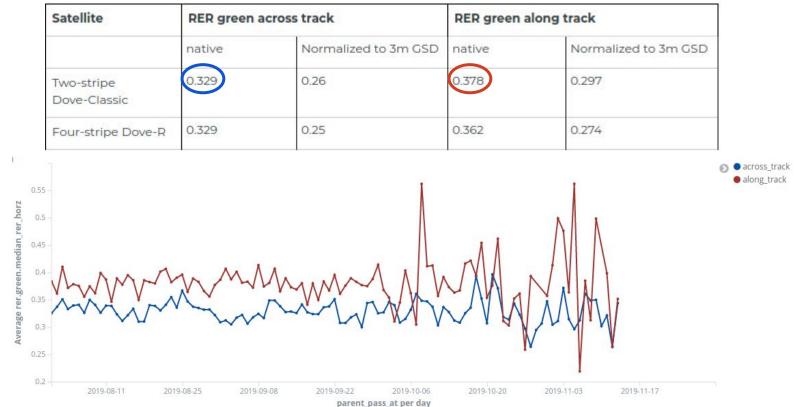
Average snr50.SNR50



SNR50 - measured from the raster data at 50% of the dynamic range of each scene



LI DATA QUALITY REPORT PLANETSCOPE Focus



LI DATA QUALITY REPORT PLANETSCOPE Product Anomalies

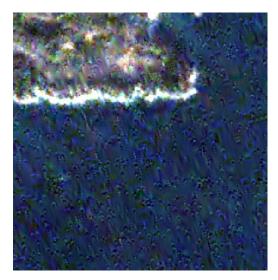
Major known anomalies, actively being worked on and planned to be fixed in the future

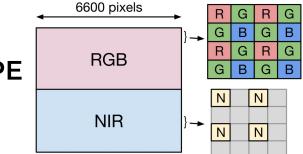
- Blurry overlap between successive scenes
- Tonal difference between successive scenes
- Saturation and Blooming significantly less frequent in Dove-R
- Tap imbalance
- NIR misalignment only Dove-Classic
- Misalignment between successive scenes
- Missing scenes in a Strip
- Frame-rate issue

LI DATA QUALITY REPORT PLANETSCOPE

Product Features - Dove-Classic

- J2K compression artifacts
- Zipper artifact through debayering





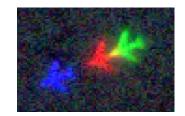


LI DATA QUALITY REPORT PLANETSCOPE

Product Features - Dove-R

- Clouds
- Planes
- Steep terrains
- Waves







Region I: band 4 Region II: band 5 Region III: band 13 Region IV: band 2

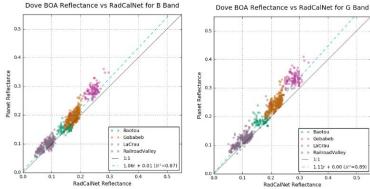


L2 Data Quality Report PlanetScope

Woody Island, South China Sea – March 28, 2018

L2 DATA QUALITY REPORT PLANETSCOPE

- No formal product requirements exists •
- Radiometric Accuracy of Surface • **Reflectance Product**
- Product Anomalies
- Product Features



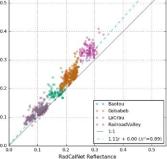
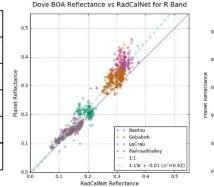
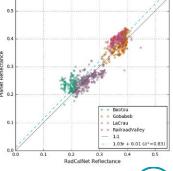


Table 1: Measured Performances for Doves							
Band	Absolute Accuracy %	Precision %	Uncertainty % (1 sigma)				
Blue	10.42	13.59	17.13				
Green	11.62	11.90	16.64				
Red	10.30	11.32	15.31				
NIR	7.91	11.81	14.21				



Dove BOA Reflectance vs RadCalNet for N Band



Future products The Planet Team, Planet Labs, Inc.

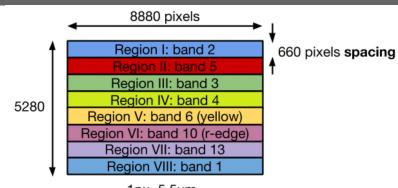


Otago, New Zealand – July 31, 2019

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L3d LAS	3D mesh	TBD 3D mesh from single capture 7.5km x 7.5km						1 day	G3	R5	orders API	

SuperDove 8-band sensor layout



1px=5.5um

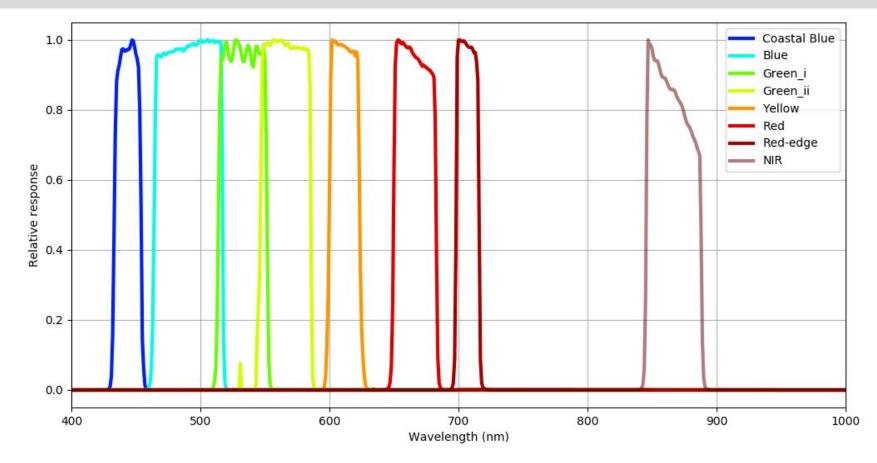
Band	Name	Notes	Wavelength (fwhm)	spatial sampling	GSD (m)	L _{ref} (W sr- ¹ um ⁻¹ m ⁻²)	SNR @ L _{ref} (t=10ms)*
1	Coastal Blue		443 (20)	0.25x	12	130	193
2	Blue	core visible bands	490 (50)	1x	3	130	170
3	Green I		531 (36)	1x	3	130	150
4	Green II		565 (36)	1x	3	130	154
5	Red		665 (31)	1x	3	130	138
6	Yellow	sediments, PC	610 (20)	1x	6	70	63
10	Red edge I	important for data compatibility with Sentinel-2	705 (15)	1x	6	70	57
13	NIR	narrow NIR	865 (40)	0.5x	6	130	137



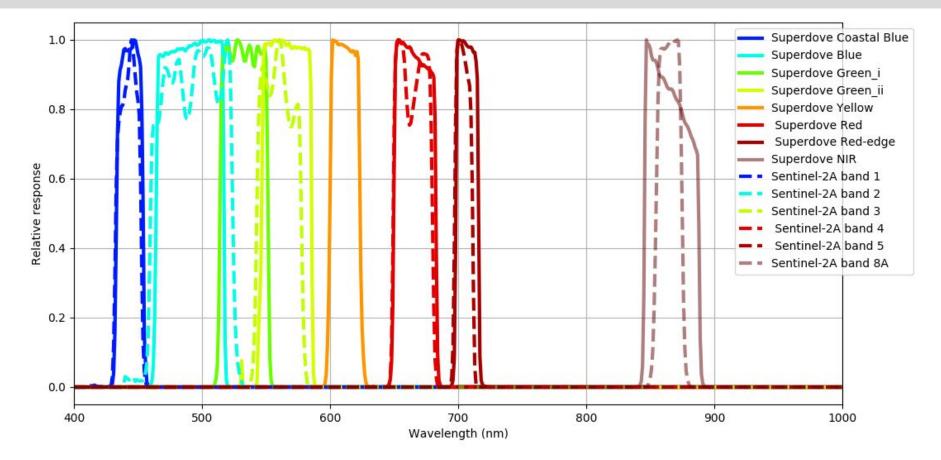
Patent Pending (US20180098014A1)

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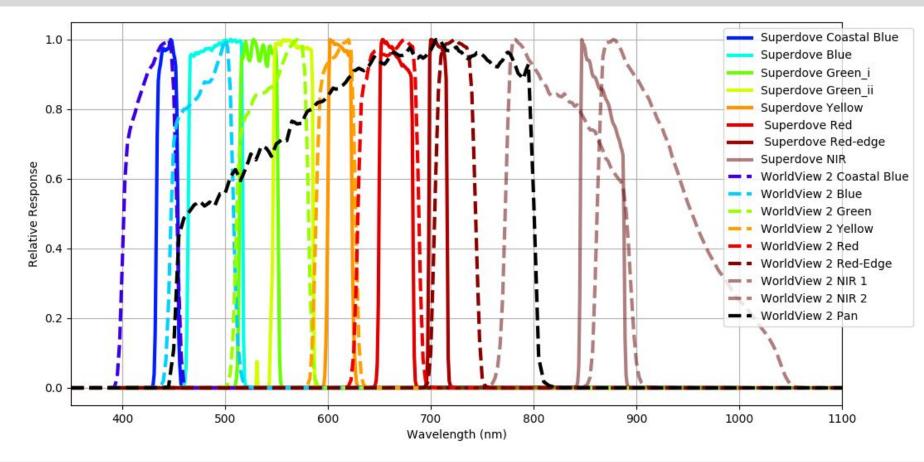
Superdove RSR (from manufacturer data)



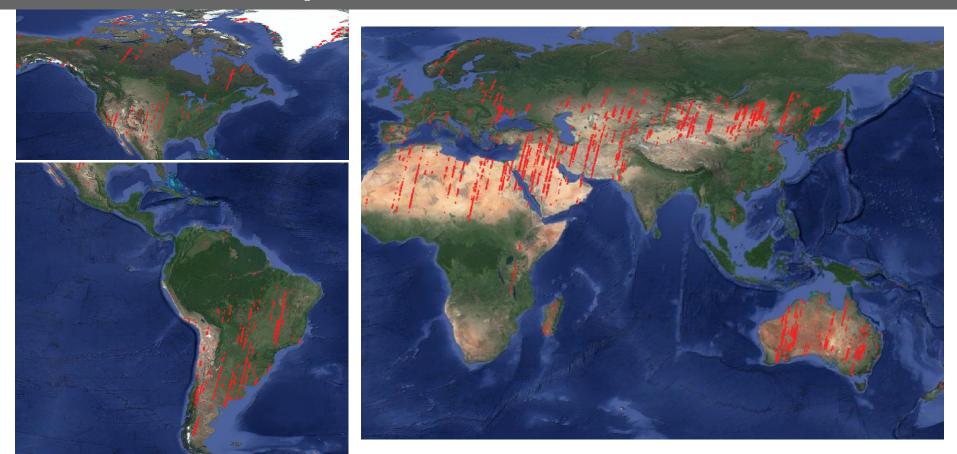
RSR comparison with Sentinel-2



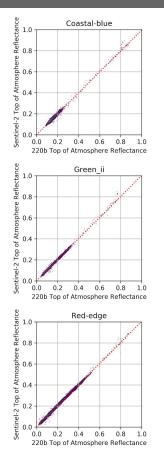
RSR comparison with WorldView 2

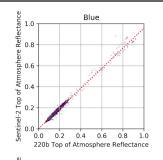


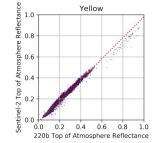
Global crossovers between a Superdove and Sentinel-2 for September

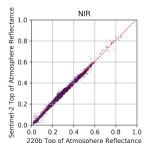


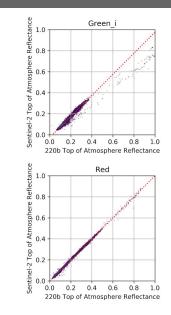
Global crossovers between a Superdove and Sentinel-2 for September







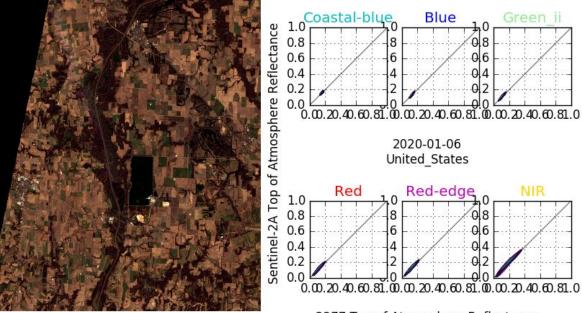




All 9304 orthotile events between a Superdove and Sentinel-2 for September. This dataset covers 19 separate dates in September and shows the results of the initial calibration.

United_States - 2020-01-06

2277

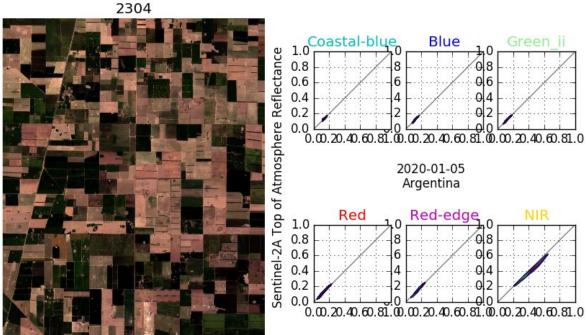


2277 Top of Atmosphere Reflectance

Sentinel-2A



Argentina - 2020-01-05



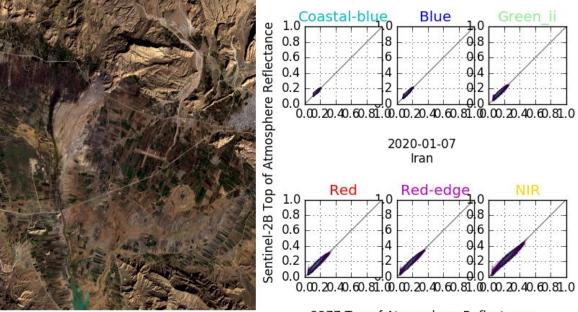
2304 Top of Atmosphere Reflectance

Sentinel-2A



Iran - 2020-01-07

2277

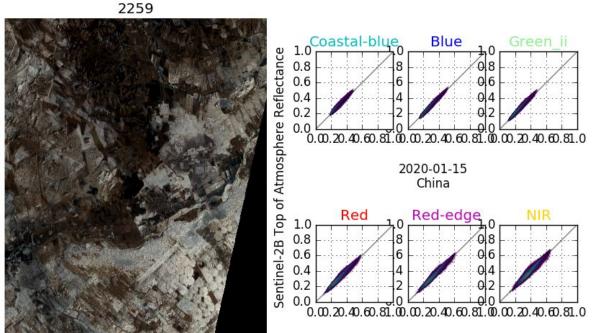


2277 Top of Atmosphere Reflectance

Sentinel-2B



China - 2020-01-15

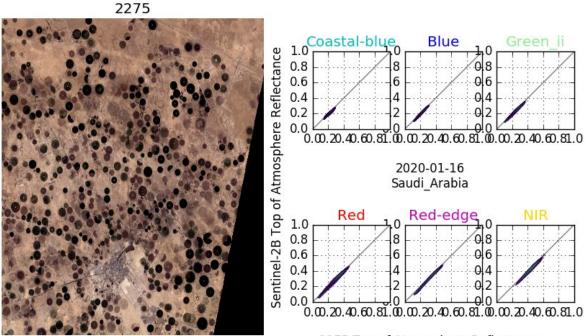


2259 Top of Atmosphere Reflectance

Sentinel-2B



Saudi_Arabia - 2020-01-16



2275 Top of Atmosphere Reflectance

Sentinel-2B

